PHD2 Guiding

C. Johnson

3/16/2018

updated Oct 3, 2018 by P Gabor & C Johnson

All of the required software is currently installed on the vattcontrol server; login as vattobs.

The legacy *VATT Guider App* only controls the stepper motors in the guide box.^{*} Guiding is done with *PHD2* !

(*) When using VATT4k and GUFI, these motors move the two filter wheels for the science camera, the guider camera's filter wheel, the guider camera's 3-axis translation stage, and the stage carrying the center mirror and the U mirror.

- start indiserver
 - $\circ~$ click the indiserver icon on the desktop
 - $\circ\,$ (a terminal window should appear)
- start phd2 guiding
 - $\circ\,$ click the PHD2 icon on the desktop
 - $\circ\,$ (the PHD2 application should appear)
- configure phd2
 - 1. in the Main tool bar, click icon that looks like a usb male connector
 - (connect equipment window should appear)
 - 2. in connect equipment window verify the following settings:
 - equipment profile "vatt imagers" or "vatt spec" depending on your instrument (the imagers are 4k CCD and GUFI),
 - camera type "INDI Camera",
 - mount type "INDI Mount",
 - aux type "None"
 - 3. in connect equipment window, in the camera row, click on the icon that looks like a screwdriver and wrench in an "X"
 - (INDI Configuration window should appear)
 - 4. in INDI Configuration window verify the following settings:
 - Hostname: localhost
 - port: 7600
 - driver: Apogee CCD

- Dual CCD: Main
- 5. click the INDI button near the bottom of the window
 - (INDI options window should appear)
- 6. select the Apogee CCD tab
- 7. verify the following settings:
 - in the port section network is selected
 - in the network section:
 - subnet: 10.0.255.255
 - Note the 4K guider is being repaired currently. We are using the VATTspec guider for all guiding. In practice this means the ip:port will be 10.0.3.12:2571
 - offset guider (used with imagers) ip:port : 10.0.3.14:2571; slit plate guider (used with VATTspec): 10.0.3.12:2571
- 1. click the connect button in the Connection field
 - $\circ\,$ (after a few seconds, a bunch of new fields and tabs should appear)
 - (The message "[ERROR] Model is not supported by the INDI Apogee driver" may mean that the camera is not powered up.)
- 2. near the bottom of the window, turn on the cooler
- 3. IF YOU ARE GOING TO BE AUTOGUIDING:
 - $\circ\,$ click on the "INDI-VATT-GUIDE" TAB
 - click "Connect"
 - $\circ\,$ (a UT clock should appear and begin incrementing.)
- 4. exit the INDI options window
- 5. click OK in the INDI Configuration window
- 6. click Connect in the Connect Equipment window, in the camera section
 - (the button should now say Disconnect)
- 7. IF YOU ARE GOING TO BE AUTOGUIDING:
 - in INDI Configuration window verify the following settings:
 - Hostname: localhost
 - port: 7600
 - driver: VATT-GUIDE-INDI
 - Port: [empty]
 - $\circ\,$ exit the INDI Configuration window
 - \circ click Connect in the Connect Equipment window, in the mount section
 - \circ (the button should now say <code>Disconnect</code>)
- 8. click Close in the Connect Equipment window
- 9. In the Main tool bar (it may be positioned anywhere in the window),
 - click the Advanced setup (brain icon) button (second from the right); a new window should appear.
- 10. Set binning to the allowed maximum of 8×8 :
 - Select the Camera tab,
 - \circ in the group Camera-specific properties, set binning to 8 (pull down selector).
 - [Note. Ostensibly, binning can be set via INDI options as NxM where N and M may take any value you wish. This feature does not work. Binning can really be set only via "brain" button.]
- 11. IF YOU WILL NOT BE AUTOGUIDING: Disable mount guide output:
 - Select the Guiding tab,
 - in the group Shared parameters disable mount guide output (uncheck the box); Guide output DISABLED should appear in the lower left of the main window. This should prevent PHD2 accidentally interfering, e.g., with the PEPSI guider.

- 12. Set up automatic frame capture:
 - Select the Global tab,
 - $^{\circ}$ check Enable diagnostic image logging, then
 - \circ in the group Save Guider Images check Until this count is reached, and

3/4

- $\circ\,$ set the value (100 is the maximum).
- $\circ\,$ the files are stored on the <code>vattcontrol</code> server
- The Dark Library is located in the directory /home/vattobs/.phd2/.
- \circ The directory /home/vattobs/PHD2/PHD2_CameraFrames... is automatically created for the session.
- If you need to capture more than 100 images, make a renamed copy of the session directory; new *fits* files should start populating the original sesson directory.
- Start Imaging
- 1. in the bottom left of the PHD2 window there is a button with 2 arrows forming a circle. Click that button.
- 2. the button should gray out, the stop sign button should turn red, and images should start appearing
- Start Guiding
- 1. change the exposure time setting and contrast slider to find an appropriate guide star.
- 2. Click on the guide star
- 3. click on the circular icon i the tool bar that looks like a target

Offset Guider Stage

Note: All numbers are GUI units. The travel limits are accurate but the diagram is only an approximation.

30 30 <td< td=""><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td></td<>																				
80 80 <td< td=""><td>9</td><td>0 -8</td><td>30 -7</td><td>70 .</td><td>-60 -</td><td>-50 -4</td><td>0 </td><td>0 -2</td><td>0 –1</td><td>0</td><td>0 1</td><td>02</td><td>03</td><td>30 4</td><td>0 5</td><td>5<mark>0 (</mark></td><td>30 7</td><td>70 8</td><td>30 9</td><td>30</td></td<>	9	0 -8	30 -7	70 .	-60 -	-50 -4	0 	0 -2	0 –1	0	0 1	02	03	30 4	0 5	5 <mark>0 (</mark>	30 7	70 8	30 9	30
70	90																			
70	•																			1_
80 90 <td< td=""><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td></td<>																				
50 40 30 20 10 0 10 0 10 10 10 10 10 10	70																			
40 40 <td< td=""><td>60</td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td></td<>	60																			
30 30 <td< td=""><td>50</td><td></td><td></td><td></td><td>_</td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td></td<>	50				_															
30 30 <td< td=""><td>40</td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td><u> </u></td><td></td><td></td><td></td><td></td></td<>	40															<u> </u>				
20 10 0 10 10 10 20 10 20 10 10 20 10 10 10 10 10 10 10 10 10 1																				
10 0	30																			
0 0	20				1															
10 TRAVEL LIMITS 20 OffsetX: -108, +101 OffsetY: -29, +95 Focus: -56.7, +4.59 Approximate size of the Andor CCD at this scale.	10				┨─															┢
20 TBAVEL LIMITS OffsetX: -108, +101 OffsetY: -29, +95 Focus: -56.7, +4.59 Approximate size of the Andor CCD at this scale.	0																			
20 TBAVEL LIMITS OffsetX: -108, +101 OffsetY: -29, +95 Focus: -56.7, +4.59 Approximate size of the Andor CCD at this scale.	10																			
OffsetX: -108, +101 OffsetY: -29, +95 Focus: -56.7, +4.59 Approximate size of the Andor CCD at this scale.								то	AVEL	L INAL	re									Ţ
Approximate size of the Andor CCD at this scale.	-20											04								
Approximate size of the Andor CCD at this scale.								Of	setX:	-10	8, +1 ,+ ^g	01 95 4 5 0								
Approximate size of the Andor CCD at this scale. The camera's true FOV is 3'47" x 2'50".								+0	cus:	-56	./, +	4.59								-
Approximate size of the Andor CCD at this scale. The camera's true FOV is 3'47" x 2'50".																				
					Appro The c	ximate amera'	size (s true	of the FOV	Andoi is 3'41	r CCD 7" x 2'	at thi 50".	s sca	le.							

From: https://lavinia.as.arizona.edu/~tscopewiki/ - **MOON**

Permanent link: https://lavinia.as.arizona.edu/~tscopewiki/doku.php?id=phd2:phd2_guiding&rev=1556251003



Last update: 2019/04/25 20:56